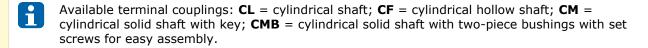




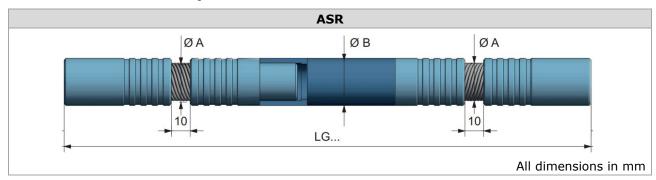
Features at a glance

Semi-rigid shafts type ASR provide an economical and practical solution to transfer the rotary movement between two aligned elements ensuring an optimal and long-lasting efficiency of motion transmission in case of limited misalignments due to construction or installation.

- Universal applicability, high reliability, maintenance-free and easy-of-use.
- Suitable for manual and motorised drives.
- Simple and quick installation, without the need for other supports.
- Rigid section is made of aluminium, terminal couplings made of solid stainless steel (AISI 303).



Dimensions and efficiency table



Version	Flexible shaft	External cover Torque		Weight
	Ø A	Ø B	Nm	g
ASR-6	6	12	3	600
ASR-10	10	14	7.5	750
ASR-15	15	20	12	2050
ASR-20	20	25	18.5	3400

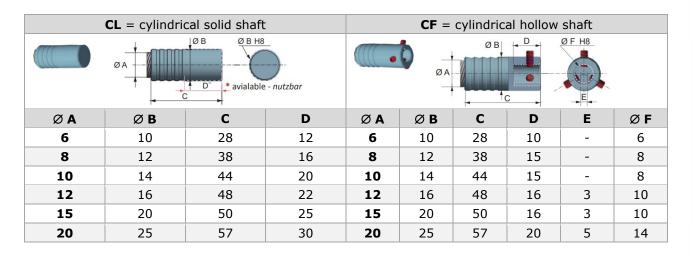
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Control



Terminal couplings for TR, ASR, GR made of solid stainless steel (AISI 303), available versions

Q	CL	CF	СМ	СМВ	Q = cylindrical square shaft			
		9.		100		ØA	C	В
Legend						T	▼ C	
Ø A	Ø A Diameter of flexible shaft						В	С
Ø B	Ø B Diameter of square shaft						5	30
С	C Total length						6.5	35
D	D Available length / bore depth				10		8 - 8.5	40
E Key					12		10	40
Ø F Diameter hollow-/solid shaft				15		12 - 13	45	
ØG	Ø G Outer diameter bushing						16.5 - 17.5	45



	CM = cylindrical solid shaft with key CMB = cylindrical solid shaft, two-piece bushings								shings			
Ø B D Ø F H8					0 0	ØA -	ØВ	ØG	ØF H8			
ØA	Ø B	С	D	E	ØF	ØA	ØB	С	D	E	ØF	ØG
6	10	28	10	-	6	6	10	10	39	-	6	14
8	12	38	14	-	8	8	12	12	53	-	8	22
10	14	44	14	-	8	10	14	14	59	_	8	22
12	16	48	15	3	10	12	16	16	64	3	10	24
15	20	50	15	3	10	15	20	20	66	3	10	24
15	20	50	15	5	14 *	15	20	20	76	5	14 *	32 *
20	25	57	20	5	14	20	25	25	78	5	14	32

* optional

All dimensions in mm

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Measure Indicate Control Sensors Mechanics Accessory



Dimensions and efficiency tables

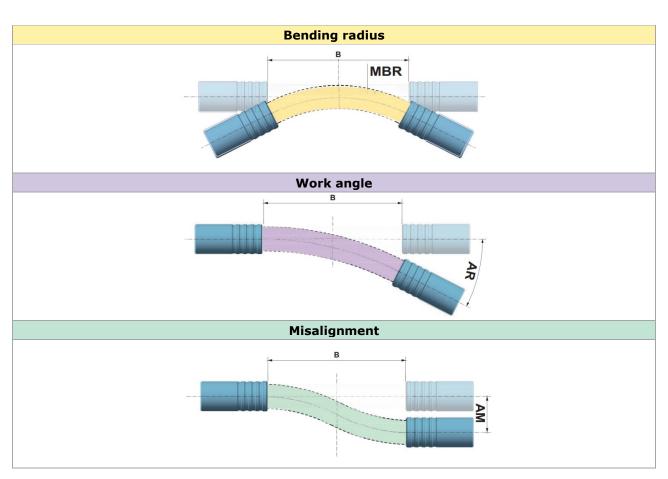
Flexibility and minimum bending radius

Flexibility and minimum bending radius are important factors especially if the shaft is exposed to severe bending during its use.



Make sure that the smallest bending radius applied to the power transmission is greater than the permissible minimum bending radius. If the bending radius falls below the permissible radius during operation, the shaft will be permanently deformed and will lose its strength and service life and may thus break prematurely.

Up to this radius, it is possible to bend the transmission during operation without damage or excessive reduction of service life.



Ø	В	MBR	AR	АМ
Flexible shaft Diameter (mm)	Flexible shaft Length (mm)*	Min. bending radius (mm)	Work angle (°)	Misalignment (mm)
6	10	70	4.09	0.36
8	10	90	3.18	0.28
10	10	130	2.20	0.20
12	10	160	1.79	0.16
15	10	300	0.95	0.08
20	10	400	0.72	0.06

^{*} for **GR** type shafts, the length of the flexible shaft is fixed at 10 mm.

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^{*} for **ASR** type shafts, there are two flexible shafts, each 10 mm long.



Max. torque / Angle							
Ø	В	Т	ф				
Flexible shaft Diameter (mm)	Flexible shaft Length (mm)*	Max. torque Nm	Rotation angle (°)				
6	10	3.0	0.79				
8	10	4.5	0.67				
10	10	7.5	0.74				
12	10	9.0	0.50				
15	10	12.5	0.30				
20	10	18.5	0.17				

^{*} for **GR** type shafts, the length of the flexible shaft is fixed at 10 mm.

^{*} for **ASR** type shafts, there are two flexible shafts, each 10 mm long.

Max. torque / Angle with opposite direction							
Ø	В	Т	ф				
Flexible shaft Diameter (mm)	Flexible shaft Length (mm)*	Max. torque Nm	Rotation angle (°)				
6	10	1.6	0.79				
8	10	2.5	0.67				
10	10	4.2	0.74				
12	10	5.8	0.50				
15	10	8.75	0.30				
20	10	12.95	0.17				

^{*} for **GR** type shafts, the length of the flexible shaft is fixed at 10 mm.

^{*} for **ASR** type shafts, there are two flexible shafts, each 10 mm long.



Direction of rotation and winding

Flexible shafts differ both in their construction and in their direction of winding A left-wound shaft (related to its outermost layer) can transmit a higher torque in clockwise direction than in counter-clockwise direction. A right-wound shaft can transmit a higher torque in counter-clockwise direction than in clockwise direction.

Outermost layer **left-wound**, for **operation in clockwise** (right-hand) **direction**. Outermost layer **right-wound**, for **operation in counter-clockwise** (left-hand) **direction**.

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Ordering example

Type ASR - 12 - 500 - DX - CL-CM

ASR

Diameter

12 = semi-rigid shaft Ø12 mm

14 = semi-rigid shaft Ø14 mm

20 = semi-rigid shaft Ø20 mm

25 = semi-rigid shaft Ø25 mm

Total length (mm)

In xxx mm (on request)

Rotation

DX = for operation in clockwise (right-hand) direction SX = for operation in counter-clockwise (left-hand) direction

Terminal couplings (indication per shaft end)

CL = cylindrical shaft

CF = cylindrical hollow shaft

CM = cylindrical solid shaft with key

CMB = cylindrical solid shaft with two-piece bushings

Q = cylindrical square shaft

Other versions that cannot be generated from the order code are available on request as special versions

Manufacturer:



The manufacturer reserves the right to make changes to the products that it deems necessary for their improvement without prior notice.

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Measure Indicate Control Sensors Mechanics Accessory